A Hyper-sequent Calculus for INL

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Junhua Yu A Hyper-sequent Calculus for INL

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Outline

- Backgrounds
 - Neighborhood semantics & 'Basic' neighborhood logic NL
 - 'Instantial' neighborhood logic INL
 - Expressive power & Axiomatization
- Proof Theory
 - Semantic tableau & Hyper-sequent calculus HSinl
 - Soundness, (Cut)-admissibility, & Completeness
 - Lyndon interpolation
- Future directions

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Abbreviation: "nbd" means "neighborhood"

Background Joint work with

Johan van Benthem, Nick Bezhanishvili, Sebastian Enqvist

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• Frame: $\mathfrak{F} = (W, \sigma)$

- $W \neq \emptyset$, a domain;
- $\sigma: W \mapsto 2^{2^{W}}$, a nbd function.
- Model: $\mathfrak{M} = (\mathfrak{F}, V)$
 - F, a nbd frame;
 - $V: W \mapsto 2^{\mathcal{P}}$, a propositional valuation.
- Remarks:
 - Nbd semantics is general
 - Specified properties of nbd functions
 - each state has a nbd,
 - $\{w\}$ is a nbd of w (resp. $\emptyset, W, ...$),
 - each nbd is non-empty,
 - each nbd of w contains w,
 - each state has exactly 1 nbd,
 - nbd is closed under

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Basic nbd logic NL

Basic modal language: unary operator □ (◊ as defined).

- Truth definition a $\exists \forall$ reading of \Box :
 - $\mathfrak{M}, w \vDash \Box \alpha$ iff $(\exists N \in \sigma(w)) (\forall n \in N) \mathfrak{M}, n \vDash \alpha$.
 - a neighborhood (of the current state) has α true everywhere inside.
- Some schemes of normal K are NOT valid:
 - $\nvDash \Box(p \rightarrow q) \rightarrow (\Box p \rightarrow \Box q),$
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• Axiomatization:

- (axiom and rule) Schemes of classical propositional calculus.
- Rule scheme RE (rule of replacement)

$$\frac{\alpha \leftrightarrow \beta \quad \phi}{\phi'}$$

where ϕ' is ϕ with an occurrance of α replaced by β

• $\Box(\alpha \wedge \beta) \rightarrow \Box \alpha \wedge \Box \beta$.

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Same frames/models with an "instantial" language:

- Operator (with any positive finite arity) $\Box(\alpha_i, ..., \alpha_j; \alpha_0)$.
- Truth definition a "∃(∃,...,∃; ∀)" reading of □:

• $\mathfrak{M}, w \vDash \Box(\alpha_1, ..., \alpha_j; \alpha_0)$ iff

$$(\exists N \in \sigma(w)) \begin{cases} (\forall n \in N) \mathfrak{M}, n \models \alpha_0 \\ (\exists n_1 \in N) \mathfrak{M}, n_1 \models \alpha_1 \\ \vdots \\ (\exists n_j \in N) \mathfrak{M}, n_j \models \alpha_j \end{cases}$$

• a neighborhood (of the current state) has

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• Some invalid schemes:

- $\nvDash \neg \Box$ (; \bot) (empty neighborhoods are permitted)
 - cf. a validity: $\vDash \neg \Box(\alpha; \bot)$.
- $\nvDash \square(; \top)$ (a state can have no neighborhoods).
- $\nvDash \Box(\alpha; \psi) \land \Box(\beta; \psi) \to \Box(\alpha, \beta; \psi)$
 - (neighborhoods given by premises may be distinct).
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• Some invalid schemes:

• $\nvDash \neg \Box(; \bot)$ (empty neighborhoods are permitted)

• cf. a validity: $\vDash \neg \Box(\alpha; \bot)$.

- $\nvDash \square(; \top)$ (a state can have no neighborhoods).
- $\nvDash \Box(\alpha; \psi) \land \Box(\beta; \psi) \rightarrow \Box(\alpha, \beta; \psi)$

(neighborhoods given by premises may be distinct).

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- Let n = 0 in $\Box(\phi_1, ..., \phi_n; \phi)$.
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- (Basic bisimulation test): if $w \Rightarrow w'$, i.e.:
 - V(w) = V'(w'),
 - $\forall N \in \sigma(w). \exists N' \in \sigma(w'). \forall n' \in N'. \exists n \in N. (n \rightleftharpoons n'),$
 - $\forall N' \in \sigma(w'). \exists N \in \sigma(w). \forall n \in N. \exists n' \in N'. (n \rightleftharpoons n');$

then w and w' agree on all formulas in the basic language.

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B.t.w., an instantial bisimulation should should take care of both directions:

•
$$V(w) = V'(w')$$
,

- if $\forall N \in \sigma(w) . \exists N' \in \sigma(w').$ $[[\forall n' \in N' . \exists n \in N . (n \rightleftharpoons n')] \& [\forall n \in N . \exists n' \in N' . (n \rightleftharpoons n')]],$
- if $\forall N' \in \sigma(w') . \exists N \in \sigma(w)$. $[[\forall n \in N . \exists n' \in N' . (n \rightleftharpoons n')] \& [\forall n' \in N' . \exists n \in N . (n \rightleftharpoons n')]].$

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- *L* mon:

 $\Box(\alpha_1,...,\alpha_j,\phi;\alpha_0) \to \Box(\alpha_1,...,\alpha_j,\phi \lor \psi;\alpha_0)$

Inst:

 $\Box(\alpha_1,...,\alpha_j,\eta;\alpha_0) \to \Box(\alpha_1,...,\alpha_j,\eta \land \alpha_0;\alpha_0)$

Norm:

 $eg \Box(lpha_1,...,lpha_j,ot;lpha_0)$

• Case:

 $\Box(\alpha_1,...,\alpha_j;\alpha_0) \to (\Box(\alpha_1,...,\alpha_j,\delta;\alpha_0) \lor \Box(\alpha_1,...,\alpha_j;\alpha_0 \land \neg \delta))$

Weak:

 $\Box(\alpha_1, \alpha_2, ..., \alpha_j; \alpha_0) \to \Box(\alpha_2, ..., \alpha_j; \alpha_0)$

• Dupl:

 $\Box(\alpha_1,...,\alpha_j;\alpha_0) \rightarrow \Box(\alpha_1,...,\alpha_j,\alpha_i;\alpha_0) \qquad \text{where } i \in \{1,...,j\}$

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• Some Derivable Schemes:



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Some Derivable Schemes:

- $\vdash \Box(\alpha_1,...,\alpha_i,\gamma,\delta,\beta_1,...,\beta_j;\psi) \rightarrow \Box(\alpha_1,...,\alpha_i,\delta,\gamma,\beta_1,...,\beta_j;\psi)$
 - Together with Weak and Dupl, we can read 'instance-formulas' as a finite set.

• $\vdash \Box(\alpha_1, ..., \alpha_j; \alpha_0) \rightarrow \Box(\alpha_1, ..., \alpha_j, \top; \alpha_0)$, when j > 0• Not valid when j = 0. • $\frac{\phi \rightarrow \psi}{\Box(\alpha_1, ..., \alpha_j; \phi) \rightarrow \Box(\alpha_1, ..., \alpha_j; \psi)}$ • R - mon as a rule scheme. • $\frac{\phi \rightarrow \psi}{\Box(\alpha_1, ..., \alpha_j, \phi; \alpha_0) \rightarrow \Box(\alpha_1, ..., \alpha_j, \psi; \alpha_0)}$ • L - mon as a rule scheme.

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Some Derivable Schemes:

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, when $j > 0$

•
$$R - mon$$
 as a rule scheme.

$$\phi \! \rightarrow \! \psi$$

$$\Box(\alpha_1,...,\alpha_j,\phi;\alpha_0) \to \Box(\alpha_1,...,\alpha_j,\psi;\alpha_0)$$

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INL - axiomatization

Some Derivable Schemes:



• Together with *Weak* and *Dupl*, we can read 'instance-formulas' as a finite set.

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$$\vdash \Box(\alpha_1, ..., \alpha_j; \alpha_0) \rightarrow \Box(\alpha_1, ..., \alpha_j, \top; \alpha_0)$$
, when $j > 0$

$$\phi \rightarrow \psi$$

$$\Box(\alpha_1,...,\alpha_j;\phi) \rightarrow \Box(\alpha_1,...,\alpha_j;\psi)$$

$$\frac{\phi \to \psi}{\Box(\alpha_1, \dots, \alpha_j, \phi; \alpha_0) \to \Box(\alpha_1, \dots, \alpha_j, \psi; \alpha_0) }$$

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INL - axiomatization

Some Derivable Schemes:

- $\vdash \Box(\alpha_1,...,\alpha_i,\gamma,\delta,\beta_1,...,\beta_j;\psi) \rightarrow \Box(\alpha_1,...,\alpha_i,\delta,\gamma,\beta_1,...,\beta_j;\psi)$
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$$\vdash \Box(\alpha_1,...,\alpha_j;\alpha_0) \rightarrow \Box(\alpha_1,...,\alpha_j,\top;\alpha_0)$$
, when $j > 0$

$$\frac{\phi \to \psi}{\Box(\alpha_1, ..., \alpha_i; \phi) \to \Box(\alpha_1, ..., \alpha_i; \psi)}$$

•
$$R - mon$$
 as a rule scheme.

$$\phi \rightarrow \psi$$

$$\Box(\alpha_1, ..., \alpha_j, \phi; \alpha_0) \rightarrow \Box(\alpha_1, ..., \alpha_j, \psi; \alpha_0)$$

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• Satisfiability problem of INL is *PSPACE*-complete.

- Faithful embeddings $K \hookrightarrow \mathsf{INL} \hookrightarrow K \oplus K;$
- Both K and $K \oplus K$ are *PSPACE*-complete.

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Proof Theory



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General idea of semantic tableau

- In order to prove ϕ , start with the goal of satisfying $\neg \phi$
- Reduce goals to subgoals (usually on subformulas)

Rules

- Impossible goals are "closed", otherwise "open"
 - Impossible have \perp or 'both α and $\neg \alpha$ ';
 - "Open" tableaus provide hints to counter-models (of ϕ);
 - "Closed" tableaus are defined as proofs (of ϕ).
- Rules for classical propositional logic

||...|| means branching

$$\frac{\neg \neg \phi}{\phi} \quad \frac{\alpha \land \beta}{\alpha} \quad \frac{\neg (\alpha \lor \beta)}{\neg \alpha} \quad \frac{\neg (\alpha \rightarrow \beta)}{\alpha} \quad \frac{\neg (\alpha \land \beta)}{||\neg \alpha|| \neg \beta||} \quad \frac{\alpha \lor \beta}{||\alpha|| \beta||} \quad \frac{\alpha \rightarrow \beta}{||\neg \alpha|| \beta||}$$
$$\frac{\beta}{\beta} \quad \frac{\beta}{\beta} \quad \frac{\beta}{\beta} \quad \frac{\beta}{\beta} \quad \frac{\beta}{\beta}$$

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$$\frac{\neg \neg \phi}{\phi} \quad \frac{\alpha \land \beta}{\alpha} \quad \frac{\neg (\alpha \lor \beta)}{\neg \alpha} \quad \frac{\neg (\alpha \to \beta)}{\alpha} \quad \frac{\neg (\alpha \land \beta)}{||\neg \alpha|| \neg \beta||} \quad \frac{\alpha \lor \beta}{||\alpha|| \beta||} \quad \frac{\alpha \to \beta}{||\neg \alpha|| \beta||}$$
$$\frac{\beta}{||\neg \alpha|| \beta||} \quad \frac{\alpha \to \beta}{||\neg \alpha|| \beta||}$$

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• INL needs (at least) a modal rule.

- A □-formula requires a nbd (with certain properties);
 A ¬□-formula refutes any nbd (with certain properties).
- □'s do not work together to close a goal; they each does, together with all ¬□'s in the same goal.
- The rule takes from a goal:
 - one □-formula, and
 - and any number of $\neg\Box$ -formulas

(with variant numbers of instances):

$$\square(\alpha_1, ..., \alpha_j; \alpha_0) \neg \square(\beta_1^1, ..., \beta_{j_1}^1; \beta_0^1) :$$

$$\neg\Box(\beta_1^k,...,\beta_{j_k}^k;\beta_0^k)$$

Junhua Yu A Hyper-sequent Calculus for INL

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Junhua Yu A Hyper-sequent Calculus for INL

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$$\begin{array}{c} \Box(\alpha_1, ..., \alpha_j; \alpha_0) \\ \neg \Box(\beta_1^1, ..., \beta_{j_1}^1; \beta_0^1) \\ \vdots \\ \neg \Box(\beta_1^k, ..., \beta_{j_k}^k; \beta_0^k) \end{array}$$

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$$\begin{array}{c}
\Box(\alpha_{1},...,\alpha_{j};\alpha_{0}) \\
\neg\Box(\beta_{1}^{1},...,\beta_{j_{1}}^{1};\beta_{0}^{1}) \\
\vdots \\
\neg\Box(\beta_{1}^{k},...,\beta_{j_{k}}^{k};\beta_{0}^{k}) \\
\end{array}$$

- □(α₁,..., α_j; α₀) requires a nbd with (generally) *j* states.
 Each nbd is consistent, if all its states are.
- $\forall i \in \{1, ..., k\}, \neg \Box(\beta_1^i, ..., \beta_{i}^i; \beta_0^i)$ requires that

either - β_0^i fails at some state,

or - β_h^i fails at each state for some $h \in \{1, ..., j_i\}$.

• $\prod_{z=1}^{k} (j_z + 1)$ options in total. Index possible nbd's by the option it takes, e.g., $\langle J(1), ..., J(k) \rangle$.

$$\begin{array}{c} \Box(\alpha_1, ..., \alpha_j; \alpha_0) \\ \neg \Box(\beta_1^1, ..., \beta_{j_1}^1; \beta_0^1) \\ \vdots \\ \neg \Box(\beta_1^k, ..., \beta_{j_k}^k; \beta_0^k) \end{array} \\ \hline \end{array}$$

- □(α₁,..., α_j; α₀) requires a nbd with (generally) *j* states.
 Each nbd is consistent, if all its states are.
- ∀i ∈ {1,...,k}, ¬□(βⁱ₁,...,βⁱ_{ji}; βⁱ₀) requires that either - βⁱ₀ fails at some state,

or - β_h^i fails at each state for some $h \in \{1, ..., j_i\}$.

• $\prod_{z=1}^{k} (j_z + 1)$ options in total. Index possible nbd's by the option it takes, e.g., $\langle \underline{l}(1), \dots, \underline{l}(\underline{k}) \rangle$.

$$\begin{array}{c} \Box(\alpha_1, ..., \alpha_j; \alpha_0) \\ \neg \Box(\beta_1^1, ..., \beta_{j_1}^1; \beta_0^1) \\ & \vdots \\ \neg \Box(\beta_1^k, ..., \beta_{j_k}^k; \beta_0^k) \end{array} \\ \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \left\| \begin{array}{c} |\alpha_0 \wedge \sigma \wedge & \neg \beta_h^i|_{\sigma \in \{\alpha_x\}_{x=1}^j \cup \{\neg \beta_0^i\}} \end{array} \right\| \end{array} \\ \end{array}$$

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- $\forall i \in \{1, ..., k\}, \neg \Box (\beta_1^i, ..., \beta_{j_i}^i; \beta_0^i)$ requires that either β_0^i fails at some state,

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• $\prod_{z=1}^{k} (j_z + 1)$ options in total.

Index possible nbd's by the option it takes, e.g., $\langle I(1), ..., I(k) \rangle$.

$$\begin{array}{c} \Box(\alpha_1, ..., \alpha_j; \alpha_0) \\ \neg \Box(\beta_1^1, ..., \beta_{j_1}^1; \beta_0^1) \\ \vdots \\ \neg \Box(\beta_1^k, ..., \beta_{j_k}^k; \beta_0^k) \end{array} \\ \hline \left| \left| \alpha_0 \wedge \sigma \wedge \bigwedge_{i \in \{1, ..., k\}}^{l(i) \neq 0} \neg \beta_{l(i)}^i \right|_{\sigma \in \{\alpha_x\}_{x=1}^j \cup \{\neg \beta_0^y\}_{y \in \{1, ..., k\}}^{l(y) = 0}} \right| \right|_{l \in \bigotimes_{z=1}^k \{0, ..., j_z\}}$$

- □(α₁,..., α_j; α₀) requires a nbd with (generally) *j* states.
 Each nbd is consistent, if all its states are.
- $\forall i \in \{1, ..., k\}, \neg \Box (\beta_1^i, ..., \beta_{j_i}^i; \beta_0^i)$ requires that either β_0^i fails at some state,

or - β_h^i fails at each state for some $h \in \{1, ..., j_i\}$.

• $\prod_{z=1}^{k} (j_z + 1)$ options in total. Index possible nbd's by the option it takes, e.g., $\langle \underline{l}(1), ..., \underline{l}(k) \rangle$.

$$\begin{array}{c} \Box(\alpha_{1},...,\alpha_{j};\alpha_{0})\\ \neg\Box(\beta_{1}^{1},...,\beta_{j_{i}}^{1};\beta_{0}^{1})\\ \vdots\\ \neg\Box(\beta_{1}^{k},...,\beta_{j_{k}}^{k};\beta_{0}^{k}) \end{array} \\ \hline \left| \left| \alpha_{0} \wedge \sigma \wedge \bigwedge_{i \in \{1,...,k\}}^{l(i)\neq 0} \neg\beta_{l(i)}^{i} \right|_{\sigma \in \{\alpha_{x}\}_{x=1}^{j} \cup \{\neg\beta_{0}^{y}\}_{y \in \{1,...,k\}}^{l(y)=0}} \right| \right|_{l \in \bigotimes_{z=1}^{k} \{0,...,j_{z}\}}$$

• It is $\prod_{z=1}^{k} (j_z + 1)$ -branching

In order to close a tableau, each branch has to be closed.

Branch correspond to neighborhoods of the current state.

Each branch offers a hyper-node

A collection of regular nodes (labeled by formulas).

To close a branch, it is enough to close one node in the hyper-node.

Nodes correspond to states in the neighborhood.

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It is destructive

Formulas (used or not) above the line cannot be used any longer (on this branch) to trigger a rule or to close a branch.

• An example $\vdash \Box(\phi \lor \chi; \theta) \rightarrow \Box(\phi; \theta) \lor \Box(\chi; \theta)$

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- TABinl is sound and complete
 - The direct proof of completeness requires an extraction of counter-model out of a 'systematical-yet-failed' implement of rules, and hence is ugly
- TABinl offers a decision procedure
- TABinl indicates a way to some real proof-theory
 - a hyper sequent calculus

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• Primitive connectives: $\{\bot, \rightarrow, \Box\}$ (classical)

- Multi-set-based, G3-style
 - No Exchange
 - Built-in Weakening and Contraction
 - Easier proofs of (Cut)-admissibility
- Hyper-sequent
 - $|\Gamma_1 \Rightarrow \Delta_1|...|\Gamma_n \Rightarrow \Delta_n|$ finite multi-set of regular sequents 'standing for' $\bigvee_{i=1}^n ((\bigwedge \Gamma_i) \to (\bigvee \Delta_i))$
 - Two groups of (admissible) structural rules (internal & external) (Weakening & Contraction) no Exchange
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$$\overline{G|\Pi, p \Rightarrow p, \Sigma}(Ax) \text{ and } \overline{G|\Pi, \bot \Rightarrow \Sigma}(L\bot)$$
G: meta-variable for sequent multi-sets (hyper-sequents)
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$$\frac{G|\Pi, \alpha \Rightarrow \beta, \Sigma}{G|\Pi \Rightarrow \alpha \rightarrow \beta, \Sigma}(R \rightarrow)$$
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•
$$\frac{[G|\Pi, \alpha \rightarrow \beta \Rightarrow \Sigma}{[...] \text{ stands for branches}} \left[\left| \alpha_{0}, \alpha_{X} \Rightarrow \left\{ \beta_{I(i)}^{i} \right\}_{i \in \{1, ..., k\}}^{I(i) \neq 0} \right|_{X \in \{1, ..., j\}} \right]_{I \in \bigotimes_{i=1}^{k} \{0, 1, ..., j\}} \left| \alpha_{0} \Rightarrow \beta_{0}^{y}, \left\{ \beta_{I(i)}^{i} \right\}_{i \in \{1, ..., k\}}^{I(i) \neq 0} \right|_{Y \in \{1, ..., k\}} \right]_{I \in \bigotimes_{i=1}^{k} \{0, 1, ..., j\}} (\Box)$$

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$$\overline{G|\Pi, \Box(\alpha_{1}, \dots, \alpha_{j}; \alpha_{0}) \Rightarrow \{\Box(\beta_{1}^{i}, \dots, \beta_{j}^{i})\}_{i=1}^{k}, \Sigma}$$

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HSinl is sound.

- If $\text{HSinl} \vdash |\Gamma_1 \Rightarrow \Delta_1| ... |\Gamma_n \Rightarrow \Delta_n|$, then $\text{INL} \vdash \bigvee_{i=1}^n (\bigwedge \Gamma_i \rightarrow \bigvee \Delta_i)$.
- Proved by an induction.
- For the (□) rule, a sub-induction gives a stronger form of what we need.
- HSinl is complete.
 - If INL $\vdash \phi$, then HSinl $\vdash \Rightarrow \phi$.
 - $\{\phi \mid \mathsf{HSinl} \vdash \Rightarrow \phi\}$ includes all axioms of INL.
 - $\{\phi \mid \mathsf{HSinl} \vdash \Rightarrow \phi\}$ is closed under *MP*
 - A corollary of (*Cut*)-admissibility.
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• Admissibility of (*Cut*) (no matter (*Cut*₊) or (*Cut*_×))

- In HSinI resp. "HSinI \oplus (*Cut*₊) of a certain 'degree' ":
 - Internal/External Weakening is d.p.a. (depth-preserved admissible).
 Actually, in each provable hyper-sequent there is a provable sequent.
 - For each formula α , (hyper-)sequent $\alpha \Rightarrow \alpha$ is provable.
 - External/Internal Contraction is d.p.a..
 D.p.a. of External Contraction is used when showing that of Internal Contraction
- Based on HSinl,
 - rules (Cut_+) and (Cut_\times) (at any same 'degree') are inter-derivable.
- Then, a standard double-induction works.
- Subformula property of HSinl as a corollary.

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• Lydon interpolation theorem:

(Let $\mathcal{V}^+(\alpha)/\mathcal{V}^-(\alpha)$ denotes positive/negative atoms in α) If INL $\vdash \phi \rightarrow \psi$, then there is a formula ϵ s.t.:

- $\mathcal{V}^{\pm}(\epsilon) \subseteq \mathcal{V}^{\pm}(\phi) \cap \mathcal{V}^{\pm}(\psi)$
- $\mathsf{INL} \vdash \phi \rightarrow \epsilon$ and $\mathsf{INL} \vdash \epsilon \rightarrow \psi$.

(a 'polar generalization' of Craig interpolation)

- A general form: If HSinl ⊢ Π_L, Π_R ⇒ Σ_L, Σ_R, then there is a formula ε s.t.:
 V[±](ε) ⊆ (V[∓](Π_R, Σ_L)) ∩ (V[±](Π_L, Σ_R))
 HSinl ⊢ Π_L ⇒ Σ_L, ε and HSinl ⊢ ε, Π_R → Σ_R.
- Employ a 'splitting version' of HSinl
 - each rule offers an interpolant of its conclusion built up from those of its premises;
 - cannot be included here in a readable manner.

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- $\mathcal{V}^{\pm}(\epsilon) \subseteq \mathcal{V}^{\pm}(\phi) \cap \mathcal{V}^{\pm}(\psi)$
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(a 'polar generalization' of Craig interpolation)

- A general form: If HSinl ⊢ Π_L, Π_R ⇒ Σ_L, Σ_R, then there is a formula ε s.t.:
 V[±](ε) ⊆ (V[∓](Π_R, Σ_L)) ∩ (V[±](Π_L, Σ_R))
 HSinl ⊢ Π_L ⇒ Σ_L, ε and HSinl ⊢ ε, Π_R → Σ_R.
- Employ a 'splitting version' of HSinl
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